

## 1. INTRODUCTION

The Avanti Digital Quartz Transducer Simulator substitutes a pressure/temperature transducer equipped with a two-wire serial I<sup>2</sup>C interface. It was designed to be compatible with Quartzdyne's range of digital quartz pressure transducers and facilitates testing of data acquisition systems without the need for real transducers. The simulator also features a special error mode, which simulates erratic I<sup>2</sup>C behaviour. This is useful for checking how well a data acquisition system recovers from a locked up I<sup>2</sup>C bus and whether it can detect inconsistent data values.

The simulator supports the I<sup>2</sup>C protocol enhancements introduced by Quartzdyne with ASIC V4.02 (and above). It is backward compatible with earlier versions.

The AVA-02 simulator is available in two variants:

Model number AVA-02-A:

The classic simulator with switch selectable pressure/temperature values

Model number AVA-02-B:

Introduced in 2025 this variant has all the functions of the original version, but in addition supports control of pressure/temperature values via a serial UART interface. It is supplied with a matching USB converter cable for direct connection to a PC.

A 4-channel multiplexer / RS232 level shifter (AVA-02-LS) is available separately and allows control of up to four AVA-02-B simulators through a single serial COM port (USB or old-style RS232).

## 2. HARDWARE DESCRIPTION

The simulator consists of a small standalone PCB (47mm x 60mm), containing a micro-controller and a serial EEPROM, which are both connected to the I<sup>2</sup>C bus.

There are two rotary switches (labelled PF and TF) for setting pressure and temperature values and a LED, which flashes whenever the simulator has been polled successfully.

Two jumper links (labelled A1 and A2) are provided for setting the device address, allowing up to 4 devices on the same I<sup>2</sup>C bus. The address lines are fitted with pull-up resistors and the jumpers make a connection to ground, i.e. a jumper inserted means the address line is low and a jumper removed means the address line is high. The address lines are also available externally via the 9-way D-type socket, so that alternatively the device address can be coded through ground connections on the host-board. The jumper links must be removed for this.

The table below shows the pin-out of the D-type socket. The pin-out is also printed on the bottom side of the PCB. **Note that Quartzdyne transducer cables that are terminated with a D-type plug have a different pin-out.**



|       |                    |
|-------|--------------------|
| Pin-1 | A1                 |
| Pin-2 | SCL                |
| Pin-3 | GND                |
| Pin-4 | SDA                |
| Pin-5 | +VS (2.7V to 5.3V) |
| Pin-6 | A2                 |
| Pin-7 | GND                |
| Pin-8 | GND                |
| Pin-9 | GND                |

All external connections are over voltage and reverse voltage protected. However, in order to minimise the possibility of damage through ESD, unnecessary touching of component pins and PCB pads should be avoided.

### 3. I<sup>2</sup>C INTERFACE

With the introduction of their Digital ASIC in 2009 (V4.02), Quartzdyne made some enhancements to the I<sup>2</sup>C protocol. These include a checksum as a 5<sup>th</sup> byte when reading from the transducer, and the extension of the status/control register from a single byte to 4 bytes. These enhancements are backward compatible with earlier versions, i.e. a host system designed for an earlier transducer version will still work with the latest version.

Since 2010, the Avanti Digital Quartz Transducer Simulator also supports the enhanced I<sup>2</sup>C protocol of V4.02 and later. Earlier simulators were based on Quartzdyne FPGA V3.02 and may be upgraded on request.

The Avanti Digital Quartz Transducer Simulator supports the following I<sup>2</sup>C commands. For details refer to the Quartzdyne Digital Transducer Programming Manual.

- Query the pressure counter. This returns a 32-bit pressure reading plus a check byte. Reading the check byte is optional. It may be used for validation of the pressure reading. In case a mismatch is found, the pressure value and the check byte can be read again, simply by continuing and reading 5 more bytes. When finished, the read access must be terminated by issuing an I<sup>2</sup>C STOP.
- Query the temperature counter. This returns a 32-bit temperature reading plus an optional check byte as above.
- Query the Version-ID. This returns a 32-bit version identifier plus an optional check byte as above.

- Query the status register. Up to 4 status bytes plus a check byte may be read as above, but in most applications only the information contained in the first status byte is of relevance (state of the pressure/temperature counters and the EEPROM write protection bit). The other 3 bytes are optional and have no function in the Avanti simulator, but must be included if the check byte is to be verified.
- Write to control register. Up to 4 control bytes may be written, but as above, only the first byte is of relevance in most applications. The first byte enables/disables the pressure and temperature counters and locks/unlocks the EEPROM write access. The other 3 bytes may be written, but are simply ignored by the Avanti simulator.
- Read/Write the serial EEPROM. The EEPROM is an independent device that shares the same I<sup>2</sup>C bus. The EEPROM is write protected by default and must be unlocked by writing to the control register, if its content is to be changed. The EEPROM contains four redundant sets of coefficients at address locations 0...0xFF, 0x100...0x1FF, 0x200...0x2FF and 0x300...0x3FF.

The I<sup>2</sup>C bus was developed by Philips Semiconductors (now NXP) and its specification can be downloaded from their web-site. In its standard version the I<sup>2</sup>C bus allows a maximum clock/data frequency of 100kHz, i.e. minimum high and low times of clock and data lines must be observed by the master. The I<sup>2</sup>C protocol also specifies a mechanism called 'clock stretching', which allows slaves to slow down the bus to below 100kHz.

While in the actual Quartzdyne transducer the I<sup>2</sup>C interface is implemented in an FPGA or ASIC (i.e. entirely in hardware), the Avanti simulator employs a micro-controller with bit-level I<sup>2</sup>C support (i.e. a mixture of hardware and firmware). This means that the Avanti simulator is slightly less forgiving with respect to I<sup>2</sup>C timing issues. In particular 'clock stretching' must be recognised by the master if running at high speed. This happens automatically if the host-micro uses a dedicated I<sup>2</sup>C port. However, if the I<sup>2</sup>C interface in the host is 'bit-banged' using two ordinary port pins for SCL and SDA, the host firmware should check explicitly for 'clock stretching'. This is quite simple to implement: It only requires the host firmware to make sure the SCL line actually goes high whenever the SCL pin is set high and, if necessary, to wait for this to happen before proceeding.

#### 4. VALUES RETURNED

Pressure and temperature values can be set independently by means of the two rotary switches. For positions 1...8 the returned value is the switch position multiplied by 10kHz, i.e. 10...80kHz. In switch position 0 a ramp is generated, which is repeated every 10 minutes. The pressure ramp starts at 30kHz and ramps upwards at a rate of 1Hz per second. The temperature ramp starts at 40kHz and ramps downwards at a rate of -1Hz per second. In switch position 9 the simulator runs in error mode, which generates regular I<sup>2</sup>C lockups and checksum errors (see paragraph 5 for details).

| Switch Position | PF  | Raw-Pres returned             | TF  | Raw-Temp returned            |
|-----------------|---|-------------------------------|---|------------------------------|
| 1               | 10000 Hz  | 0x005B05B1                    | 10000 Hz  | 0x005B05B1                   |
| 2               | 20000 Hz  | 0x00B60B61                    | 20000 Hz  | 0x00B60B61                   |
| 3               | 30000 Hz  | 0x01111111                    | 30000 Hz  | 0x01111111                   |
| 4               | 40000 Hz  | 0x016C16C1                    | 40000 Hz  | 0x016C16C1                   |
| 5               | 50000 Hz  | 0x01C71C72                    | 50000 Hz  | 0x01C71C72                   |
| 6               | 60000 Hz  | 0x02222222                    | 60000 Hz  | 0x02222222                   |
| 7               | 70000 Hz  | 0x027D27D4                    | 70000 Hz  | 0x027D27D4                   |
| 8               | 80000 Hz  | 0x02D82D84                    | 80000 Hz  | 0x02D82D84                   |
| 9               | 30000 Hz with regular I <sup>2</sup> C errors                       | 0x01111111                    | 40000 Hz with regular I <sup>2</sup> C errors                       | 0x016C16C1                   |
| 0               | Ramp 30000...30600 Hz at +1Hz/sec => Sawtooth edge every 10 minutes | Ramp 0x01111111... 0x01168720 | Ramp 40000...39400 Hz at -1Hz/sec => Sawtooth edge every 10 minutes | Ramp 0x016C16C1.. 0x0166A0B1 |

The simulator is shipped with coefficients pre-loaded in the EEPROM. These coefficients were taken off a real transducer and therefore produce engineering values, which represent a typical Quartzdyne transducer. Only the serial number and the calibration date were modified to reflect the simulators serial number and date of manufacture. The following table shows the psi and °C values obtained with these coefficients:

|       | PF | 10kHz                        | 20kHz                        | 30kHz                       | 40kHz                       | 50kHz                       | 60kHz                       | 70kHz                       | 80kHz                       |
|-------|----|------------------------------|------------------------------|-----------------------------|-----------------------------|-----------------------------|-----------------------------|-----------------------------|-----------------------------|
| TF    |    |                              |                              |                             |                             |                             |                             |                             |                             |
| 10kHz |    | -11421.63 psi<br>236.342 °C  | -5648.515 psi<br>236.342 °C  | -252.348 psi<br>236.342 °C  | 4842.551 psi<br>236.342 °C  | 9711.851 psi<br>236.342 °C  | 14431.22 psi<br>236.342 °C  | 19076.35 psi<br>236.342 °C  | 23722.88 psi<br>236.342 °C  |
| 20kHz |    | -8745.46 psi<br>194.991 °C   | -3710.684 psi<br>194.991 °C  | 1101.552 psi<br>194.991 °C  | 5728.189 psi<br>194.991 °C  | 10206.17 psi<br>194.991 °C  | 14572.43 psi<br>194.991 °C  | 18863.92 psi<br>194.991 °C  | 23117.58 psi<br>194.991 °C  |
| 30kHz |    | -6871.39 psi<br>150.948 °C   | -2371.768 psi<br>150.948 °C  | 2000.479 psi<br>150.948 °C  | 6262.484 psi<br>150.948 °C  | 10431.37 psi<br>150.948 °C  | 14524.28 psi<br>150.948 °C  | 18558.34 psi<br>150.948 °C  | 22550.67 psi<br>150.948 °C  |
| 40kHz |    | -5689.32 psi<br>98.854 °C    | -1569.95 psi<br>98.854 °C    | 2476.813 psi<br>98.854 °C   | 6459.496 psi<br>98.854 °C   | 10386.63 psi<br>98.854 °C   | 14266.73 psi<br>98.854 °C   | 18108.34 psi<br>98.854 °C   | 21919.97 psi<br>98.854 °C   |
| 50kHz |    | -5089.159 psi<br>33.349 °C   | -1243.407 psi<br>33.349 °C   | 2562.94 psi<br>33.349 °C    | 6333.302 psi<br>33.349 °C   | 10071.10 psi<br>33.349 °C   | 13779.75 psi<br>33.349 °C   | 17462.68 psi<br>33.349 °C   | 21123.30 psi<br>33.349 °C   |
| 60kHz |    | -4960.809 psi<br>-50.927 °C  | -1330.312 psi<br>-50.927 °C  | 2291.249 psi<br>-50.927 °C  | 5897.976 psi<br>-50.927 °C  | 9483.968 psi<br>-50.927 °C  | 13043.32 psi<br>-50.927 °C  | 16570.13 psi<br>-50.927 °C  | 20058.50 psi<br>-50.927 °C  |
| 70kHz |    | -5194.183 psi<br>-159.332 °C | -1768.852 psi<br>-159.332 °C | 1694.117 psi<br>-159.332 °C | 5167.578 psi<br>-159.332 °C | 8624.385 psi<br>-159.332 °C | 12037.38 psi<br>-159.332 °C | 15379.43 psi<br>-159.332 °C | 18623.38 psi<br>-159.332 °C |
| 80kHz |    | -5679.18 psi<br>-297.226 °C  | -2497.196 psi<br>-297.226 °C | 803.938 psi<br>-297.226 °C  | 4156.19 psi<br>-297.226 °C  | 7491.532 psi<br>-297.226 °C | 10741.93 psi<br>-297.226 °C | 13839.35 psi<br>-297.226 °C | 16715.77 psi<br>-297.226 °C |

When queried for the Version-ID, the simulator returns the value 0x0D090403, which reads as Quartzdyne Digital ASIC V4.03.

## 5. ERROR MODE

The Avanti simulator implements two error conditions when in error mode: I<sup>2</sup>C lockup and checksum error.

### a) I<sup>2</sup>C Lockup

The Philips/NXP I<sup>2</sup>C specification doesn't include any timeout mechanism. It is the responsibility of the I<sup>2</sup>C master to recover from conditions, where the I<sup>2</sup>C sequence has gone out of synch. This may happen if electrical noise is coupled into the SDA/SCL lines, or if the I<sup>2</sup>C master is reset while an I<sup>2</sup>C transfer is in progress, e.g. by a watchdog timer. Also, some of the earlier Quartzdyne transducers didn't always power up in the correct I<sup>2</sup>C state. This can lead to a situation where the SDA line is stuck low, preventing the master from generating a START or STOP. The I<sup>2</sup>C bus appears to be locked.

The master can overcome this situation by issuing 9 clock pulses while SDA is released. After a maximum of 9 cycles the slave reaches the point where it reads the acknowledgement from SDA. Since SDA is released, the slave reads this as a NACK and terminates. The master should then finish with a STOP.

The operation of such a bus recovery procedure can be checked by setting the simulator into error mode. If the pressure switch is set to position 9, the simulator locks SDA low after every 10<sup>th</sup> pressure query. Likewise, if the temperature switch is set to position 9, the simulator locks up after every 10<sup>th</sup> temperature query.

The 10<sup>th</sup> query itself is not affected and returns the correct result. However, the simulator ignores the NACK and the STOP at the end of the transfer and expects the master to clock out further data bits. The simulator is in a state as if it were interrupted during a read access, just after putting data bit-6 onto the bus. The data byte is assumed to be 0x0C (00001100), and therefore SDA is held low. A minimum of 7 clock pulses are required to clock out the remaining data bits and assert a NACK. Additional clock pulses after the NACK have no effect.

If both switches (pressure AND temperature) are in position 9, the simulator not only locks up after every 10<sup>th</sup> pressure and every 10<sup>th</sup> temperature query, but also powers up in a locked up state. Here the simulator assumes a data byte value of 0x0D (00001101) with SDA stuck at bit-5.

While SDA is stuck low, the simulator turns on the LED. If the I<sup>2</sup>C master in the host controller is implemented properly, it will be able to unlock a stuck I<sup>2</sup>C bus and no data loss or data corruption should occur.

### b) Checksum Error

If the pressure switch and the temperature switch are both set to position 9, the simulator creates additional data errors every 30sec, which result in an invalid checksum. The data

error may occur during a pressure query or a temperature query, whichever is the first after the 30sec error timer has elapsed.

In case of a data error, the MSByte of a pressure or temperature query is returned as 0x00 instead of 0x01. This shows up as a pressure frequency of 1875Hz instead of 30000Hz or a temperature frequency of 11875Hz instead of 40000Hz.

If the host controller reads and verifies the checksum it will detect a mismatch and read the data bytes again. On the second attempt the data is returned correctly and the checksum is valid.

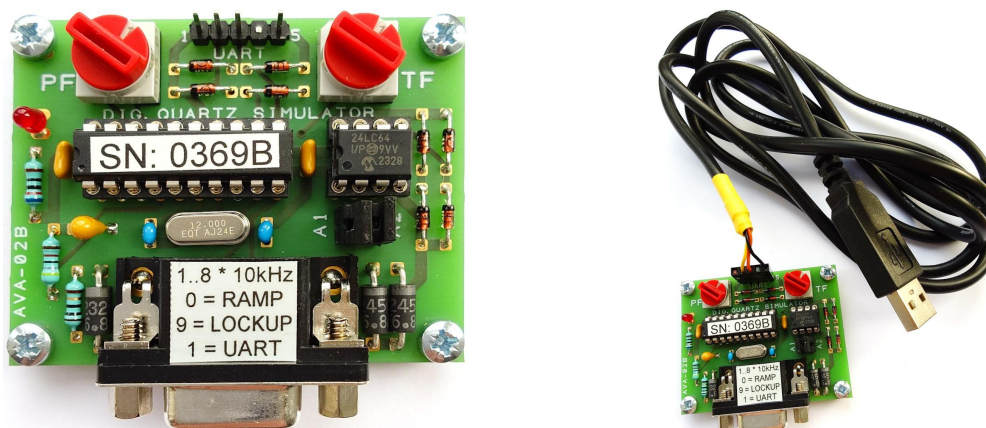
Since earlier versions of digital Quartzdyne transducers (prior to V4.02) do not return a checksum, the host controller should first check the transducer's revision code by reading the identifier, and then take action accordingly.

## 6. SERIAL PORT (AVA-02-B ONLY)

All of the above applies to both simulator variants, the AVA-02-A and the AVA-02-B, but the AVA-02-B has an additional feature. It allows pressure/temperature values to be set from a PC via a serial interface.

The AVA-02-B is shipped with a USB converter cable which plugs into a header labelled 'UART' on the simulator. The converter cable is a "TTL-232R-3V3" made by FTDI, where the pinout has been adapted to match the AVA-02-B header. It provides translation from USB to logic level RS232.

PCs running Windows 10 or later automatically recognise the cable and make it appear as a virtual COM port. Older PCs may require the installation of a driver available from [www.ftdichip.com](http://www.ftdichip.com).



The simulator is put into serial comms mode by setting its PF or TF switch (or both) to **position '1'**. The simulator then listens to commands at **1200Baud**, 1 start-bit, 8 data-bits, 1 stop-bit. Commands are all ASCII, so any terminal software can be used.

On power-up the simulator sends its firmware revision code. To set pressure, type 'p', 'q', 'r' or 's', depending on the I<sup>2</sup>C address of the simulator (see the table below). To set temperature type 't', 'u', 'v' or 'w'. Different command characters are used so that several simulators can be controlled via a single COM port (see paragraph 7).

| <b>Command Character depending on I<sup>2</sup>C Address</b> |                 |                    |
|--|-----------------|--------------------|
| <b>I<sup>2</sup>C Address</b>                                | <b>Pressure</b> | <b>Temperature</b> |
| A2 = 0 / A1 = 0 (jumpers in/in)                              | 'p'             | 't'                |
| A2 = 0 / A1 = 1 (jumpers in/out)                             | 'q'             | 'u'                |
| A2 = 1 / A1 = 0 (jumpers out/in)                             | 'r'             | 'v'                |
| A2 = 1 / A1 = 1 (jumpers out/out)                            | 's'             | 'w'                |

After the command character, type between 1 and 8 **hex digits** according to the raw pressure/temperature count required. Note that all characters are in **lower case**. Valid characters are echoed, invalid ones are not echoed and simply ignored. The echo can serve as verification of what the simulator has received. A command is terminated by <CR> which is echoed as <CR><LF>.

After receiving the terminating <CR> the simulator checks that the hex value entered is within a range of 26bits (0...0x03FFFFFF), which is the maximum value a Quartzdyne transducer can return. If out of range, the firmware responds with a '?' and the invalid entry is ignored.

Note that pressure/temperature values set through the serial port are volatile and will be lost as soon as power is removed or the switch position is changed.

#### Example for A2=0/A1=1:

```
Sent:   q 0 1 3 e 9 3 e 9 <cr>
Echoed: q 0 1 3 e 9 3 e 9   <cr><lf>
Sent:   u 0 1 9 9 9 9 9 9 <cr>
Echoed: u 0 1 9 9 9 9 9 9   <cr><lf>
```

Sets pressure count to 0x013E93E9 = 20878313 = 35000.0 Hz and  
 temperature count to 0x01999999 = 26843545 = 45000.0 Hz resulting in  
 P = 4506.957psi / T = 68.113 °C.

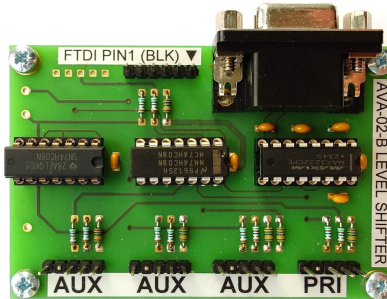
If your terminal software supports scripts/macros and if these are sent in quick succession (end to end), it may be necessary to add a dummy character after the terminating <CR> to allow enough time for the complete echo (two characters) to get out. So for instance send <CR><LF> instead of just <CR>.

## **7. MULTIPLEXER / RS232 LEVEL SHIFTER**

A 4-channel multiplexer / RS232 level shifter (AVA-02-LS) is available as an extra if more than one simulator is to be controlled via a single COM port. The AVA-02-LS combines the RX/TX signals of up to 4 simulators and makes them available via the standard USB cable that comes with the AVA-02-B or alternatively via an old-style RS232 connection, so that any old PC can be used.



Connections to the simulators are made with the jumper leads supplied. Note that one of the headers on the AVA-02-LS is labelled "PRI" (primary) while the other three are labelled "AUX". Make sure that always one of the simulators is plugged into the "PRI" header, since it's through this connection that the level shifter draws its power.



## 8. SIMULATOR SPECIFICATION

|   |   |
|---|---|
| Supply Voltage  | 2.7V – 5.3V (absolute maximum)  |
| Typ. Supply Current (LED off, nothing connected to UART header) | 2.0mA @ 3.0V<br>2.3mA @ 3.3V<br>4.2mA @ 5.0V  |
| Typ. Supply Current while LED flashes                           | 4.0mA @ 3.0V<br>4.7mA @ 3.3V<br>9.1mA @ 5.0V  |
| Update Rate when Ramping  | 33ms  |
| Interface   | Quartzdyne compatible I <sup>2</sup> C; SCL and SDA require pull-up resistors on host board |
| Connector   | 9-way D-Type socket (female)<br>5-way header for RS232 (AVA-02-B only)                      |
| Circuit Board Dimensions  | 60mm x 47mm (excluding D-Type socket)   |

## 9. ACKNOWLEDGEMENTS AND FURTHER INFORMATION

Quartzdyne is a trademark of Quartzdyne Inc (now part of ChampionX). Information on their range of digital pressure transducers can be downloaded from their website at <http://www.quartzdyne.com>. The following documents are of particular interest:  
 DigitalTransSpec.pdf - Digital Quartz Pressure Transducer Specifications  
 DigitalTransProg.pdf - Digital Transducer Programming Manual

I<sup>2</sup>C is a trademark of NXP Semiconductors (formerly Philips). Specifications and application notes can be downloaded from their web-site at <http://www.nxp.com>. The following documents are of particular interest:  
 i2c.bus.specification.pdf - I<sup>2</sup>C Specification and User Manual Rev.03 / 2007  
 i2cbits.zip - Software Implemented I2C Drivers ('bit-banged')

Avanti Part Number: AVA-02-

Avanti Serial Number:

Tested: